Modern C++ Programming

14. Advanced Topics

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Agenda

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Move Semantic

Overview

Move semantics is about transferring ownership of resources from one object to another

It is different from **copy semantic** which give you a duplicate of the original resource

In C++ every expression is either an **rvalue** or an **lvalue**

- a **lvalue** represents an object that occupies some identifiable location in memory
- a **rvalue** is an expression that does not represent an object occupying some identifiable location in memory

```
int x = 5;  // x is a lvalues
int y = 10; // y is a lvalues

int z = (x * y); // y is an lvalue, (x * y) is an rvalue
```

C++11 introduces a new kind of reference called **rvalue** reference `X&&`

- An **rvalue** reference only binds to an `rvalue`, that is a temporary
- A **lvalue** reference binds to an `lvalue`, or to an `rvalue` if the `lvalue` reference is `const`

```
int main() {
    int        x = 5;  // x is a lvalues
    const int& y = 10; // y is a lvalues reference

    const int& z = (x * y); // z is a lvalue const reference
                            // to an rvalue
    int&&      rv1 = (x * y);
//  int&&      rv2 = x;  // x is not an rvalue
}
```

lvalues and rvalues


```
struct A {};

void f(A& a) {}

void g(const A& a) {}

void h(A&& a) {}

int main() {
    A a;
    f(a);  // ok, f() can modify "a"
    g(a);  // ok, f() cannot modify "a"
//  h(a);  // compile error!! f() does not accept rvalues

//  f(A()); // compile error!! f() does not accept rvalues
    g(A()); // ok, f() cannot modify the object A()
    h(A()); // ok, f() can modify the object A()
}
```

The problem:

```
#include <algorithm>
#include <iostream>
struct AW { // array wrapper
  int  _size;
  int* _array;

  AW(int size) : _size(size) {
      array = new int[size];
  }
  AW(const AW& obj) : _size(obj._size){
      std::cout << "copy";
      _array = new int[_size];
      std::copy(obj._array,
                obj._array + _size,
                _array);
  }
  ~AW() {
      delete[] _array;
  }
};
```

```
#include <vector>

int main() {
    std::vector<AW> vector;
    vector.push_back( AW(10) );
    // use vector
}
```

`AW(10)` cannot be passed by reference, otherwise `_array` is deallocated and it is no more valid in `vector`

Pass-by-value forces using the copy constructor, but it performs redundant operations (constructor + copy) since `AW(10)` is not more needed in `main`

Class prototype with support for move semantic:

```
class X {
public:
    X();                    // default constructor

    X(const X& obj);  // copy constructor

    X(X&& obj);        // move constructor

    X& operator=(const X& obj); // copy assign operator

    X& operator=(X&& obj);      // move assign operator

    ~X();                  // destructor
private:
    Y _data;
};
```

```
X(X&& obj);
```

Move constructor semantic:

(1) Shallow copy of `obj` data members (in contrast to deep copy)

(2) Release any `obj` resources and reset all data members (pointer to `nullptr`, size to 0, etc.)

```
X& operator=(X&& obj);
```

Move assignment semantic:

(1) Release any resources of `this`

(2) Shallow copy of `obj` data members (in contrast to deep copy)

(3) Release any `obj` resources and reset all data members (pointer to `nullptr`, size to 0, etc.)

(4) Return `*this`

```
AW(AW&& obj) {
    _size  = obj._size;   // (1) shallow copy
    _array = obj._array;  // note the difference with the copy constructor
    obj._size  = 0;       // (2) release obj (it is not more valid)
    obj._array = nullptr; // obj has been moved to *this
}

AW& operator=(AW&& obj) {
    delete[] _array;      // (1) release this
    _size  = obj._size;   // (2) shallow copy
    _array = obj._array;
    delete[] obj._array;  // (3) release obj
    obj._size = 0;
    return *this;         // (4) return *this
}
```

C++11 provides the method `std::move` (`<utility>`) to indicate that an object may be "moved from"

It allows to efficient transfer resources from an object to another one

Considering the class array wrapper `AW` with support for move semantic:

```
#include <vector>

int main() {
    std::vector<AW> vector;
    vector.push_back( AW(10) );  // call move constructor
    // use vector

    AW aw(10);
    vector.push_back( aw );      // call copy constructor

    vector.push_back( std::move(aw) );  // call move constructor
}
```

Universal Reference

The `&&` syntax has two different meanings depending on the context it is used

- **`rvalue`** reference
- Either **`rvalue`** reference or **`lvalue`** reference (*universal reference*, cit. Scott Meyers)

```cpp
struct A {};

void f(A&& a) {} // rvalue only

template<typename T>
void g(T&& t) {} // universal reference

int main() {
    A a;
    f(A());  // ok
//  f(a); // compile error (only rvalue)
    g(A());  // ok
    g(a);    // ok
}
```

```cpp
void h() {
    A   a1;
    A&& a2 = A(); // ok
//  A&& a3 = a1;  // compile error
                  // (only rvalue)

    auto&& a4 = A(); // ok
    auto&& a5 = a1;  // ok

    A&& a6 = std::move(a1); // ok
}
```

Reference Collapsing Rules

Before C++11 (C++98, C++03), it was not allowed to take a reference to a reference (`A& &` causes a compile error)

C++11, by contrast, introduces the following **reference collapsing rules**:

```
template<typename T>
void f(T& a) {}    // compile error in C++98/03
int main() {       // (with gcc), no errors in C++11
    int a = 3;     // (and clang with C++98/03)
    f<int&>(a);
}
```

Type	Reference		Result
A&	&	→	A&
A&	&&	→	A&
A&&	&	→	A&
A&&	&&	→	A&&

cit: www.aristeia.com/BookErrata/emc++-errata.html

Type Deduction (Template)

Type	T	T&	const T&	T&&
`A a`	A	A&	const A&	A& &&
`A&`	A	A&	const A&	A& &&
`const A&`	A	const A&	const A&	const A& &&
`A&&`	A	const A&	const A&	A& &&
`A*`	A*	A*&	cosnt A*&	A*& &&
`const A*`	const A*	const A*&	cosnt A*&	const A*& &&
`A[3]`	A*	(A&)[3]	const (A&)[3]	(A&)[3] &&
`const A[3]`	const A*	const (A&)[3]	const (A&)[3]	const (A&)[3] &&

Type Deduction (auto)

Type	auto	auto&	const auto&	auto&&
A a	A	A&	const A&	A&
A&	A	A&	const A&	A&
const A&	A	const A&	const A&	const A&
A&&	A	A&	const A&	A&
A*	A*	A*&	const A*&	A*&
const A*	const A*	const A*&	const A*&	const A*&
A[3]	A*	(A&)[3]	const (A&)[3]	(A&)[3]
const A[]	const A*	const (A&)[3]	const (A&)[3]	const (A&)[3]

Type Deduction (std::initializer_list)

```
#include <utility>
template<typename T>
void f(T a) {}

template<typename T>
void g(std::initializer_list<int>) {}

// auto h1() { return { 1, 2, 3 }; } // compile error

auto h2() { // ok
    return std::initializer_list<int>({ 1, 2, 3 });
}

int main() {
    auto x = { 1, 2, 3 };   // x: std::initializer_list<int>
//  f( { 1, 2, 3 } );       // compile error
    g( { 1, 2, 3 } );       // ok
}
```

Type Deduction (`decltype`)

`decltype` can be combined with `auto` to prevent *type decay*

```
struct A {};

auto g() {            // auto : A
    A a;  A& a1 = a;
    return a1;
}
decltype(auto) g() {  // decltype(auto) : A& !!
    A a;  A& a1 = a;
    return a1;
}
decltype(auto) g() {  // decltype(auto) : A& !!
    A a;
    return (a);  // without ( expr ) decltype(auto) : A
}
int main() {
    A a;
    const A& a1 = a;
    auto       x = a1;       // x is of type "A"
    decltype(auto) y = a1; // y is of type "const A&"
}
```

Copy elision is a compiler optimization technique that eliminates unnecessary copying/moving of objects (it is defined in the C++ standard)

A compiler avoids omitting copy/move operations in these cases:

- **RVO (Return Value Optimization)** means the compiler is allowed to avoid creating *temporary* objects for return values
- **NRVO (Named Return Value Optimization)** means the compiler is allowed to return an object (with automatic storage duration) without invokes copy/move constructors

Copy Elision and RVO

```
AW f1() {
    return AW(10);   // RVO
}

AW f2() {
    AW aw(10);
    return aw;       // NRVO
}

AW f5() {
    AW aw(10);
    return std::move(aw);
}   // move constructor

AW f3(bool b) {
    return b ?  AW(10) : AW(5); // RVO
}

AW f4(bool b) {
    AW aw1(10), aw1(5);
    return b ? aw1(10) : aw1(5);
}   // copy constructor
```

```
AW&& f6() {
    return AW(10);
    std::move(aw); // RVO
}
AW aw_global(10);

AW&& f7() {
    return aw_global;
}     // copy constructor

struct B {
    AW aw(10);
} b;

AW f8() {
    return b.aw; // copy constructor
}

int main() {
    AW aw = f1();  // ok RVO
    aw    = f1();
}     // move operator= (no RVO)
```

Perfect Forwarding

`std::forward` (`<utility>`) forwards the argument to another function with the value category it had (`lvalue`/`rvalue` and `const`/`volatile` modifiers) when passed to the calling function (*perfect forwarding*)

```cpp
#include <iostream>
template<typename T>
void g(T& t) {
    std::cout << "lvalue";
}   // g(T&) is never called if g(A(10))

template<typename T>
void g(T&& t) {
    std::cout << "rvalue";
}

// template<typename T>
// void g(T t) {
//   when call f1() T cannot
//   deduce T& or T&&
```

```cpp
template<typename T>
void f1(T&& obj) {
    g( obj );
}

template<typename T>
void f2(T&& obj) {
    g( std::forward<T>(obj) );
}

int main(int argc) {
    g ( A(10) ); // print "rvalue"
    f1( A(10) ); // print "lvalue"!!
    f2( A(10) ); // print "rvalue"
}
```

Compiler Implicitly Declares

Special Members

compiler implicitly declares

user declares	default constructor	destructor	copy constructor	copy assignment	move constructor	move assignment
Nothing	defaulted	defaulted	defaulted	defaulted	defaulted	defaulted
Any constructor	not declared	defaulted	defaulted	defaulted	defaulted	defaulted
default constructor	user declared	defaulted	defaulted	defaulted	defaulted	defaulted
destructor	defaulted	user declared	defaulted	defaulted	not declared	not declared
copy constructor	not declared	defaulted	user declared	defaulted	not declared	not declared
copy assignment	defaulted	defaulted	defaulted	user declared	not declared	not declared
move constructor	not declared	defaulted	deleted	deleted	user declared	not declared
move assignment	defaulted	defaulted	deleted	deleted	not declared	user declared

Full story: `www.slideshare.net/ripplelabs/howard-hinnant-accu2014`

Type Deduction

Type Deduction

When you call a template function, you may omit any template argument that the compiler can determine or deduce (inferred) by the usage and context of that template function call [IBM]

- The compiler tries to deduce a template argument by comparing the type of the corresponding template parameter with the type of the argument used in the function call
- Similar to function default parameters, (any) template parameters can be deduced only if they are at end of the parameter list

Full Story: IBM Knowledge Center

Example

```
template<typename T>
int add1(T a, T b) {  return a + b; }

template<typename T, typename R>
int add2(T a, R b) { return a + b;  }

template<typename T, int B>
int add3(T a) { return a + B; }

template<int B, typename T>
int add4(T a) { return a + B; }

int main() {
add1(1, 2);       // ok
// add1(1, 2u);     // the compiler expects the same type
add2(1, 2u);      // ok (add2 is more generic)
add3<int, 2>(1); // "int" cannot be deduced
add4<2>(1);       // ok
}
```

Type Deduction (Pass-by-Reference)

Type deduction with references

```
template<typename T>
void f(T& a) {}

template<typename T>
void g(const T& a) {}

int main() {
int        x = 3;
int&       y = x;
const int& z = x;
f(x);   // T: int
f(y);   // T: int
f(z);   // T: const int // <-- !! it works...but note that
g(x);   // T: int       //     it does not for f(int& a)!!
g(y);   // T: int       //     (only non-const references)
g(z);   // T: int       // <-- see the difference
}
```

Type deduction with pointers

```
template<typename T>
void f(T* a) {}

template<typename T>
void g(const T* a) {}

int main() {
int*       x = nullptr;
const int* y = nullptr;
auto       z = nullptr;
f(x);    // T: int
f(y);    // T: const int
//  f(z);    // compile error!! z: "nullptr_t != T*"
g(x);    // T: int
g(y);    // T: int
}
```

Type Deduction (Pass-by-Pointer)

```cpp
template<typename T>
void f(const T* a) {}

template<typename T>
void g(T* const a) {}

int main() {
int*             x = nullptr;
const int*       y = nullptr;
int* const       z = nullptr;
const int* const w = nullptr;
f(x);   // T: int
f(y);   // T: int
f(z);   // T: int
//  g(x);   // compile error!! objects pointed are not constant
//  g(y);   // the same (the pointer itself is constant)
g(z);   // T: int
g(w);   // T: int
}
```

Type deduction with values

```
template<typename T>
void f(T a) {}

template<typename T>
void g(const T a) {}

int main() {
int         x = 2;
const int   y = 3;
const int& z = y;
f(x);   // T: int
f(y);   // T: int!!  (drop const)
f(z);   // T: int!!  (drop const&)
g(x);   // T: int
g(y);   // T: int
g(z);   // T: int!!  (drop reference)
}
```

Type Deduction (Pass-by-Value) 2/2

```
template<typename T>
void f(T a) {}

int main() {
int*       x = nullptr;
const int* y = nullptr;
int* const z = x;
f(x);  // T = int*
f(y);  // T = int* !! (const drop)
f(z);  // T = int* const
}
```

Type Deduction (Array)

Type deduction with arrays

```
template<typename T, int N>
void f(T (&array)[N]) {}   // type and size deduced

template<typename T, int N>
void g(T array[N]) {}

int main() {
int       x[3] = {};
const int y[3] = {};
f(x);   // T: int, N: 3
f(y);   // T: int (const drop) (pass-by-value)
//  g(x);   // compile error!! not able to deduce
}
```

Type Deduction

When you call a template function, you may omit any template argument that the compiler can determine or deduce (inferred) by the usage and context of that template function call [IBM]

- The compiler tries to deduce a template argument by comparing the type of the corresponding template parameter with the type of the argument used in the function call
- Similar to function default parameters, (any) template parameters can be deduced only if they are at end of the parameter list

Full Story: IBM Knowledge Center

Example

```cpp
template<typename T>
int add1(T a, T b) {  return a + b; }

template<typename T, typename R>
int add2(T a, R b) { return a + b;  }

template<typename T, int B>
int add3(T a) { return a + B; }

template<int B, typename T>
int add4(T a) { return a + B; }

int main() {
   add1(1, 2);        // ok
// add1(1, 2u);       // the compiler expects the same type
   add2(1, 2u);       // ok (add2 is more generic)
   add3<int, 2>(1); // "int" cannot be deduced
   add4<2>(1);        // ok
}
```

Type Deduction (Pass-by-Reference)

Type deduction with references

```
template<typename T>
void f(T& a) {}

template<typename T>
void g(const T& a) {}

int main() {
    int        x = 3;
    int&       y = x;
    const int& z = x;
    f(x);   // T: int
    f(y);   // T: int
    f(z);   // T: const int // <-- !! it works...but note that
    g(x);   // T: int       //     it does not for f(int& a)!!
    g(y);   // T: int       //     (only non-const references)
    g(z);   // T: int       // <-- see the difference
}
```

Type Deduction (Pass-by-Pointer)

Type deduction with pointers

```
template<typename T>
void f(T* a) {}

template<typename T>
void g(const T* a) {}

int main() {
    int*       x = nullptr;
    const int* y = nullptr;
    auto       z = nullptr;
    f(x);    // T: int
    f(y);    // T: const int
//  f(z);    // compile error!! z: "nullptr_t != T*"
    g(x);    // T: int
    g(y);    // T: int
}
```

Type Deduction (Pass-by-Pointer) 2/2

```
template<typename T>
void f(const T* a) {}

template<typename T>
void g(T* const a) {}

int main() {
    int*             x = nullptr;
    const int*       y = nullptr;
    int* const       z = nullptr;
    const int* const w = nullptr;
    f(x);   // T: int
    f(y);   // T: int
    f(z);   // T: int
//  g(x);   // compile error!! objects pointed are not constant
//  g(y);   // the same (the pointer itself is constant)
    g(z);   // T: int
    g(w);   // T: int
}
```

Type deduction with values

```
template<typename T>
void f(T a) {}

template<typename T>
void g(const T a) {}

int main() {
    int        x = 2;
    const int  y = 3;
    const int& z = y;
    f(x);   // T: int
    f(y);   // T: int!!  (drop const)
    f(z);   // T: int!!  (drop const&)
    g(x);   // T: int
    g(y);   // T: int
    g(z);   // T: int!!  (drop reference)
}
```

Type Deduction (Pass-by-Value)


```
template<typename T>
void f(T a) {}

int main() {
    int*       x = nullptr;
    const int* y = nullptr;
    int* const z = x;
    f(x);  // T = int*
    f(y);  // T = int* !! (const drop)
    f(z);  // T = int* const
}
```

Type deduction with arrays

```
template<typename T, int N>
void f(T (&array)[N]) {}   // type and size deduced

template<typename T, int N>
void g(T array[N]) {}

int main() {
    int       x[3] = {};
    const int y[3] = {};
    f(x);   // T: int, N: 3
    f(y);   // T: int (const drop) (pass-by-value)
//  g(x);   // compile error!! not able to deduce
}
```

Type Deduction (Conflicts)

```
template<typename T>
void add(T a, T b) {}

template<typename T, typename R>
void add(T a, R b) {}

template<typename T>
void add(T a, char b) {}

template<typename T, int N>
void f(T (&array)[N]) {}

template<typename T>
void f(T* array) {}  // <---

int main() {
    add(2, 3.0f); // ok, call add<T, R>(T, R)
//  add(2, 3);    // compile error!! (not able to decide)
    add(2, 'b');  // ok, call add(T, char)  // nearest match
    int x[3];
    f(x);         // !! call f<int>() not f<int, 3>()
}                 // see next slide for a possible solution
```

Type Deduction (Conflicts)

```
template<typename T>
void add(T a, T b) {}

template<typename T, typename R>
void add(T a, R b) {}

template<typename T>
void add(T a, char b) {}

template<typename T, int N>
void f(T (&array)[N]) {}

template<typename T>
void f(T* array) {}  // <---

int main() {
add(2, 3.0f); // ok, call add<T, R>(T, R)
//  add(2, 3);    // compile error!! (not able to decide)
add(2, 'b');  // ok, call add(T, char)  // nearest match
int x[3];
f(x);         // !! call f<int>() not f<int, 3>()
}                 // see next slide for a possible solution
```

C++ Idioms

Rule of Three

The **Rule of Three** is a rule of thumb for C++(03)

> If your class needs any of
>
> - a copy constructor `X(const X&)`
> - an assignment operator `X& operator=(const X&)`
> - or a destructor `~X()`
>
> defined explicitly, then it is likely to need all three of them

Some resources cannot or should not be copied. In this case, they should be declared as deleted

```
X(const X&) = delete
X& operator=(const X&) = delete
```

Note: many classes (such as `std` classes) manage resources themselves and should not implement copy/move constructor and assignment operator **(Rule of Zero)**

Rule of Five

The **Rule of Five** is a rule of thumb for C++11

If your class needs any of

- a copy constructor `X(const X&)`
- a move constructor `X(X&&)`
- an assignment operator `X& operator=(const X&)`
- an assignment operator `X& operator=(X&&)`
- or a destructor `~X()`

defined explicitly, then it is likely to need all five of them

Singleton

Singleton is a software design pattern that restricts the instantiation of a class to one and only one object

A common application is for logging

```
class Singleton {
public:
    static Singleton& get_instance() {  // note "static"
        static Singleton instance { ..init.. } ;
        return instance;   // destroyed at the end of the program
    }                      // initiliazed at first use

    Singleton(const& Singleton)      = delete;
    void operator=(const& Singleton) = delete;
private:
    T _data;

    Singleton( ..args.. ) {  // used in the initialization
        ...
    }
}
```

PIMPL (Opaque Pointer)

Pointer to IMPLementation (PIMPL) idiom allow removing compilation dependencies on internal class implementations and improve compile times

header.hpp

```
class A {          // the class A is responsible to allocate
public:            // and deallocate Impl* ptr
    void f() {
        ptr->f();
    }
private:
    class Impl;  // forward declaration
    Impl* ptr;   // opaque pointer
};
```

`source.cpp` (Impl actual implementation)

```
class A::Impl {
public:
    void f() {
        ..do something..
    }
};
```

CRTP Idiom 1/2

The **Curiously Recurring Template Pattern (CRTP)** is an idiom in which a class `X` derives from a class template instantiation using `X` itself as template argument

A common application is *static polymorphism*

```
template <class T>
struct Base {
    void my_method() {
        static_cast<T*>(this)->implementation();
    }
};

class Derived : public Base<Derived> {
//  void my_method() is inherited
private:
    void my_method_impl() { ... }
};
```

```cpp
#include <iostream>

template <class T>
struct Writer {
    void write(const char* str) {
        static_cast<const T*>(this)->write_impl(str);
    }
};
class CerrWriter : public Writer<CerrWriter> {
private:
    void write_impl(const char* str) {  std::cerr << str;  }
};
class CoutWriter : public Writer<CoutWriter> {
private:
    void write_impl(const char* str) {  std::cout << str;  }
};
int main() {
   CoutWritter x;
   CerrWritter y;
   x.write("abc");
   y.write("abc");
}
```

Virtual functions cannot have template arguments, but they can be emulated by using the following pattern

```
class Base {
public:
    template<typename T>
    void method(T t);    // here we want to emulate a virtual method
}
```

```
class Base {
public:
    template<typename T>
    void method(T t) {
        v_method(t);    // call the actual implementation
    }
private:
    virtual void v_method(int t)    = 0; // v_method is valid only
    virtual void v_method(double t) = 0; // for "int" and "double"
};
```

Template Virtual Functions

Actual implementations for derived class `A` and `B`

```
class AImpl : public Base {
protected:
    template<typename T>
    void t_method(T t) { // template "method()" implementation for A
        std::cout << "A " << t << std::endl;
    }
};

class BImpl : public Base {
protected:
    template<typename T>
    void t_method(T t) { // template "method()" implementation for B
        std::cout << "B " << t << std::endl;
    }
};
```

Template Virtual Functions 3/3

```cpp
template<class Impl>
class DerivedWrapper : public Impl {
private:
    void v_method(int t) {
        Impl::t_method(t);
    }
    void v_method(double t) {
        Impl::t_method(t);
    } // call the base method
};

using A = DerivedWrapper<AImpl>;
using B = DerivedWrapper<BImpl>;
```

```cpp
int main(int argc, char* argv[]) {
    A a;
    B b;
    Base* base = nullptr;

    base = &a;
    base->method(1);   // print "A 1"
    base->method(2.0); // print "A 2.0"

    base = &b;
    base->method(1);   // print "B 1"
    base->method(2.0); // print "B 2.0"
}
```

`method()` calls **`v_method()`** (pure virtual method of `Base`)

`v_method()` calls **`t_method()`** (actual implementation)

Smart pointers

Smart Pointers

Smart pointer is a pointer-like type with some additional functionality, e.g. *automatic memory deallocation* (when the pointer is no longer in use, the memory it points to is deallocated), reference counting, etc.

C++11 provides three smart pointer types:

- **`std::unique_ptr`**
- **`std::shared_ptr`**
- **`std::weak_ptr`**

Smart pointers prevent most situations of memory leaks by making the memory deallocation automatic

Full Story: embeddedartistry.com

Smart Pointers Benefits

- If a smart pointer goes *out-of-scope*, the appropriate method to release resources is called automatically. The memory is not left dangling
- Smart pointers will automatically be set to `nullptr` if not initialized or when memory has been released
- `std::shared_ptr` provides automatic reference count
- If a special `delete` function needs to be called, it will be specified in the pointer type and declaration, and will automatically be called on delete

std::unique_ptr is used to manage any dynamically allocated object that is not shared by multiple objects

```
#include <iostream>
#include <memory>
struct A {
    A()  { std::cout << "Constructor\n"; } // called when A()
    ~A() { std::cout << "Destructor\n";  } // called when u_ptr1,
};                                         // u_ptr2 are out-of-scope

int main() {
    auto raw_ptr = new A();
    std::unique_ptr<A> u_ptr1(new A());
    std::unique_ptr<A> u_ptr2(raw_ptr);
//  std::unique_ptr<A> u_ptr3(raw_ptr); // no error, but wrong!!
                                        // (same pointer)
//  u_ptr1 = &raw_ptr;  // compile error (unique pointer)
//  u_ptr1 = u_ptr2;    // compile error (unique pointer)
    u_ptr1 = std::move(u_ptr2); // delete u_ptr1;
}                               // u_ptr1 = u_ptr2;
                                // u_ptr2 = nullptr
```

`std::unique_ptr` methods

- `get()` returns the underlying pointer
- `operator*` `operator->` dereferences pointer to the managed object
- `operator[]` provides indexed access to the stored array (if it supports random access iterator)
- `release()` returns a pointer to the managed object and releases the ownership
- `reset(ptr)` replaces the managed object with `ptr`

Utility method: `std::make_unique<T>()` creates a unique pointer of a class T that manages a new object

```cpp
#include <iostream>
#include <memory>

struct A {
    int value;
};

int main() {
    std::unique_ptr<A> u_ptr1(new A());
    u_ptr1->value;      // dereferencing
    (*u_ptr1).value;    // dereferencing

    auto u_ptr2 = std::make_unique<A>();  // create a new unique pointer

    u_ptr1.reset(new A());              // reset
    auto raw_ptr = u_ptr1.release();    // release
    delete[] raw_ptr;

    std::unique_ptr<A[]> u_ptr3(new A[10]);
    auto& obj = u_ptr3[3];              // access
}
```

Implements a custom deleter

```
#include <iostream>
#include <memory>

struct A {
    int value;
};

int main() {
    auto DeleteLambda = [](A* x) {
        std::cout << "delete" << std::endl;
        delete x;
    };

    std::unique_ptr<A, decltype(DeleteLambda)>
        x(new A(), DeleteLambda);
} // print "delete"
```

std::shared_ptr is the pointer type to be used for memory that can be owned by multiple resources at one time

std::shared_ptr maintains a reference count of pointer objects. Data managed by std::shared_ptr is only freed when there are no remaining objects pointing to the data

```
#include <iostream>
#include <memory>
struct A {
    int value;
};
int main() {
    std::shared_ptr<A> sh_ptr1(new A());
    std::shared_ptr<A> sh_ptr2(sh_ptr1);
    std::shared_ptr<A> sh_ptr3(new A());
    sh_ptr3 = nullptr; // allowed, the underlying pointer is deallocated
                       //   sh_ptr3 : zero references
    sh_ptr2 = sh_ptr1; // allowed // sh_ptr1, sh_ptr2: two references
    sh_ptr2 = std::move(sh_ptr1); // allowed // sh_ptr1: zero references
}                                          // sh_ptr2: one references
```

`std::shared_ptr` (Shared Pointer)

`std::shared_ptr` methods

- `get()` returns the underlying pointer
- `operator*` `operator->` dereferences pointer to the managed object
- `use_count()` returns the number of objects referring to the same managed object
- `reset(ptr)` replaces the managed object with `ptr`

Utility method: `std::make_shared()` creates a shared pointer that manages a new object

```cpp
#include <iostream>
#include <memory>
struct A {
    int value;
};

int main() {
    std::shared_ptr<A> sh_ptr1(new A());
    auto sh_ptr2 = std::make_shared<A>();  // std::make_shared
    std::cout << sh_ptr1.use_count();  // print 1

    sh_ptr1 = sh_ptr2;                 // copy
//  std::shared_ptr<A> sh_ptr2(sh_ptr1); // copy (constructor)
    std::cout << sh_ptr1.use_count();  // print 2
    std::cout << sh_ptr2.use_count();  // print 2

    auto raw_ptr = sh_ptr1.get();      // get
    sh_ptr1.reset(new A());            // reset

    (*sh_ptr1).value = 3;              // dereferencing
    sh_ptr1->value = 2;                // dereferencing
}
```

A **std::weak_ptr** is simply a std::shared_ptr that is allowed to dangle (pointer not deallocated)

```
#include <iostream>
#include <memory>

struct A {
    int value;
};

int main() {
    auto ptr = new A();
    std::weak_ptr<A>   w_ptr(ptr);
    std::shraed_ptr<A> sh_ptr(new A());

    sh_ptr = nullptr;
//  delete sh_ptr.get(); // double free or corruption

    w_ptr = nullptr;
    delete w_ptr; // ok valid
}
```

It must be converted to `std::shared_ptr` in order to access the referenced object

`std::weak_ptr` methods

- `use_count()` returns the number of objects referring to the same managed object
- `reset(ptr)` replaces the managed object with `ptr`
- `expired()` checks whether the referenced object was already deleted (`true`, `false`)
- `lock()` creates a `std::shared_ptr` that manages the referenced object

```cpp
#include <iostream>
#include <memory>
struct A {
    int value;
};
int main() {
    auto sh_ptr1 = std::make_shared<A>();

    std::cout << sh_ptr1.use_count();  // print 1
    std::weak_ptr<A> w_ptr = sh_ptr1;
    std::cout << w_ptr.use_count();    // print 1

    auto sh_ptr2 = w_ptr.lock();
    std::cout << kk.use_count();       // print 2 (sh_ptr1 + sh_ptr2)

    sh_ptr1 = nullptr;
     std::cout << w_ptr.expired();     // print false

    sh_ptr2 = nullptr;
    std::cout << w_ptr.expired();      // print true
}
```

Concurrency

Overview

C++11 introduces the **Concurrency** library to simplify managing OS threads

```cpp
#include <iostream>
#include <thread>

void f() {
    std::cout << "first thread" << std::endl;
}

int main(){
    std::thread th(f);
    th.join();          // stop the main thread until "th" complete
}
```

How to compile:

```
$g++ -std=c++11 main.cpp -pthread
```

Example

```cpp
#include <iostream>
#include <thread>
#include <vector>

void f(int id) {
    std::cout << "thread " << id << std::endl;
}
int main() {
    std::vector<std::thread> thread_vect; // thread vector
    for (int i = 0; i < 10; i++)
        thread_vect.push_back( std::thread(&f, i) );

    for (auto& th : thread_vect)
        th.join();

    thread_vect.clear();
    for (int i = 0; i < 10; i++) {  // thread + lambda expression
        thread_vect.push_back(
            std::thread( [](){ std::cout << "thread\n"; } );
    }
}
```

Library methods:

- `std::this_thread::get_id()` returns the thread id
- `std::thread::sleep_for( sleep_duration )`
  Blocks the execution of the current thread for at least the specified `sleep_duration`
- `std::thread::hardware_concurrency()` returns the number of concurrent threads supported by the implementation

Thread object methods:

- `get_id()` returns the thread id
- `join()` waits for a thread to finish its execution
- `detach()` permits the thread to execute independently from the thread handle

```cpp
#include <chrono>   // the following program should (not deterministic)
#include <iostream> // produces the output:
#include <thread>   //    child thread exit
                    //    main thread exit
int main() {
    using namespace std::chrono_literals;
    std::cout << std::this_thread::get_id();
    std::cout << std::thread::hardware_concurrency(); // e.g. print 6

    auto lambda = []() {
        std::this_thread::sleep_for(1s); // t2
        std::cout << "child thread exit\n";
    };
    std::thread child(lambda);
    child.detach(); // without detach(), child must join() the
                    // main thread (run-time error otherwise)
    std::this_thread::sleep_for(2s);    // t1
    std::cout << "main thread exit\n";
}
// if t1 < t2 the should program prints:
//    main thread exit
```

Parameters Passing

Parameters passing *by-value* or *by-pointer* to a thread function works in the same way of a standard function. *Pass-by-reference* requires a special wrapper (`std::ref` , `std::cref`) to avoid wrong behaviors

```
#include <iostream>
#include <thread>
void f(int& a, const int& b) {
    a = 7;
    const_cast<int&>(b) = 8;
}
int main() {
    int a = 1, b = 2;
    std::thread th1(f, a, b);                    // wrong!!!
    std::cout << a << ", " << b << std::endl;    // print 1, 2!!

    std::thread th2(f, std::ref(a), std::cref(b)); // correct
    std::cout << a << ", " << b << std::endl;    // print 7, 8!!
    th1.join(); th2.join();
}
```

The following code produces (in general) a value < 1000:

```
#include <chrono>
#include <iostream>
#include <thread>
#include <vector>
void f(int& value) {
    for (int i = 0; i < 10; i++) {
        value++;
        std::this_thread::sleep_for(std::chrono::milliseconds(10));
    }
}
int main() {
    int value = 0;
    std::vector<std::thread> th_vect;
    for (int i = 0; i < 100; i++)
        th_vect.push_back( std::thread(f, std::ref(value)) );

    for (auto& it : th_vect)
        it.join();
    std::cout << value;
}
```

C++11 provide the **`mutex`** class as synchronization primitive to protect shared data from being simultaneously accessed by multiple threads

`mutex` methods:

- **`lock()`** locks the *mutex*, blocks if the *mutex* is not available
- **`try_lock()`** tries to lock the *mutex*, returns if the *mutex* is not available
- **`unlock()`** unlocks the *mutex*

More advanced mutex can be found here: `en.cppreference.com/w/cpp/thread`

C++ includes three mutex wrappers to provide safe copyable/movable objects:

- `lock_guard` (C++11) implements a strictly scope-based mutex ownership wrapper
- `unique_lock` (C++11) implements movable mutex ownership wrapper
- `shared_lock` (C++14) implements movable shared mutex ownership wrapper

Mutex


```cpp
#include <chrono>
#include <iostream>
#include <thread>
#include <vector>
void f(int& value, std::mutex& m) {
    for (int i = 0; i < 10; i++) {
        m.lock();
        value++;   // other threads must wait
        m.unlock();
        std::this_thread::sleep_for(std::chrono::milliseconds(10));
    }
}
int main() {
    std::mutex m;
    int value = 0;
    std::vector<std::thread> th_vect;
    for (int i = 0; i < 100; i++)
        th_vect.push_back( std::thread(f, std::ref(value), std::ref(m)) );
    for (auto& it : th_vect)
        it.join();
    std::cout << value;
}
```

Atomic

`std::atomic` (C++11) template class defines an atomic type that are implemented with lock-free operations (much faster than locks)

```
#include <atomic>
...  // include also: chrono, iostream, thread, vector

void f(std::atomic<int>& value) {
    for (int i = 0; i < 10; i++) {
        value++;
        std::this_thread::sleep_for(std::chrono::milliseconds(10));
    }
}
int main() {
    std::atomic<int> value(0);
    std::vector<std::thread> th_vect;
    for (int i = 0; i < 100; i++)
        th_vect.push_back( std::thread(f, std::ref(value)) );
    for (auto& it : th_vect)
        it.join();
    std::cout << value;    // print 1000
}
```

Task-based parallelism

The **`future`** library provides facilities to obtain values that are returned and to catch exceptions that are thrown by *asynchronous* tasks

Asynchronous call: `std::future async(function, args...)`
runs a function asynchronously (potentially in a new thread) and returns a `std::future` object that will hold the result

`std::future` methods:

- `T get()` returns the result
- `wait()` waits for the result to become available

`async()` can be called with two launch policies for a task executed:

- `std::launch::async` a new thread is launched to execute the task asynchronously
- `std::launch::deferred` the task is executed on the calling thread the first time its result is requested (lazy evaluation)

Task-based parallelism


```cpp
#include <iostream>
#include <vector>
#include <algorithm>
#include <numeric>
#include <future>
template <typename RandomIt>
int parallel_sum(RandomIt beg, RandomIt end) {
    auto len = end - beg;
    if (len < 1000)    // base case
        return std::accumulate(beg, end, 0);

    RandomIt mid = beg + len / 2;
    auto handle = std::async(std::launch::async, // right side
                             parallel_sum<RandomIt>, mid, end);
    int sum = parallel_sum(beg, mid);             // left side
    return sum + handle.get();                    // left + right
}
int main() {
    std::vector<int> v(10000, 1); // init all to 1
    std::cout << "The sum is " << parallel_sum(v.begin(), v.end());
}
```